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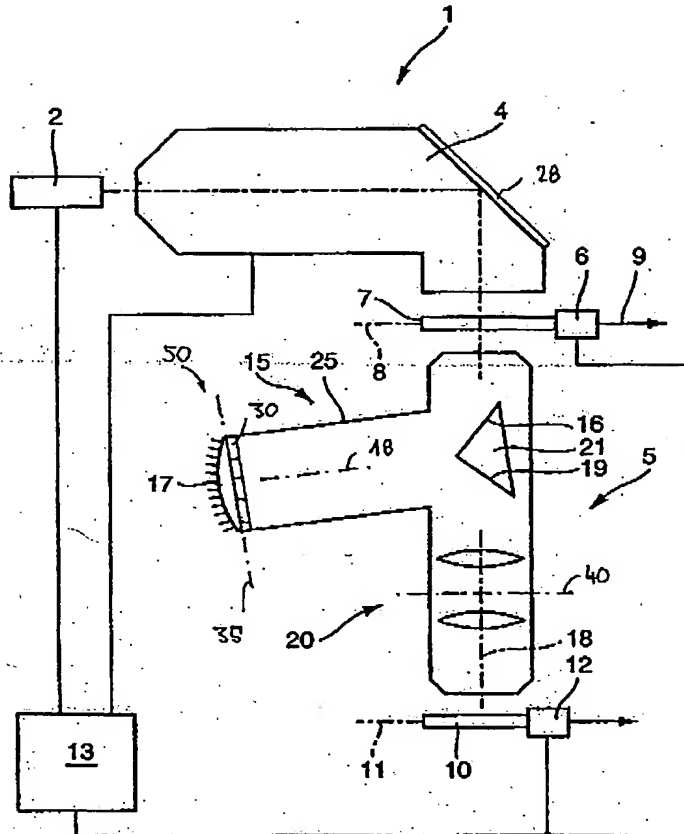


Fig. 1

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The diagram shows a mechanical system. On the left, a curved member labeled 17 is attached to a vertical rectangular support labeled 30. Two horizontal beams extend from the right side of support 30. The upper beam is labeled 23 and is inclined downwards towards the right. The lower beam is labeled 19 and is parallel to the upper one. A diagonal member, labeled 16, connects the right end of beam 23 to the right end of beam 19. At the top joint where beam 23 meets member 16, there is a counter-clockwise moment vector labeled G. At the bottom joint where beam 19 meets member 16, there is a downward-pointing force vector labeled S. At the top-right end of beam 23, there is a downward force vector labeled S and a horizontal force vector labeled P pointing to the right. At the bottom-right end of beam 19, there is a downward force vector labeled S and a horizontal force vector labeled P pointing to the right. In the middle-left area, between the two horizontal beams, there is another set of force vectors: a downward force vector labeled S and a horizontal force vector labeled P pointing to the right.

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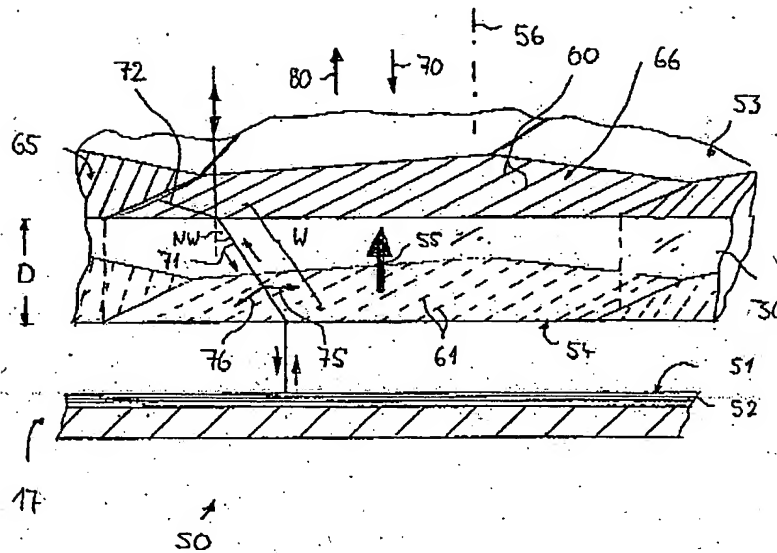


Fig. 3

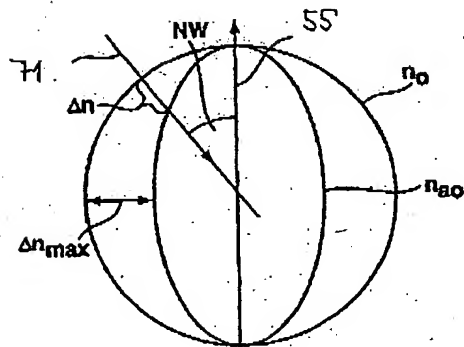


Fig. 4

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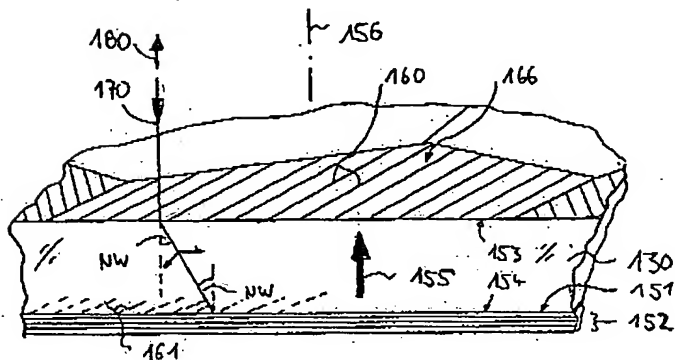


Fig. 5

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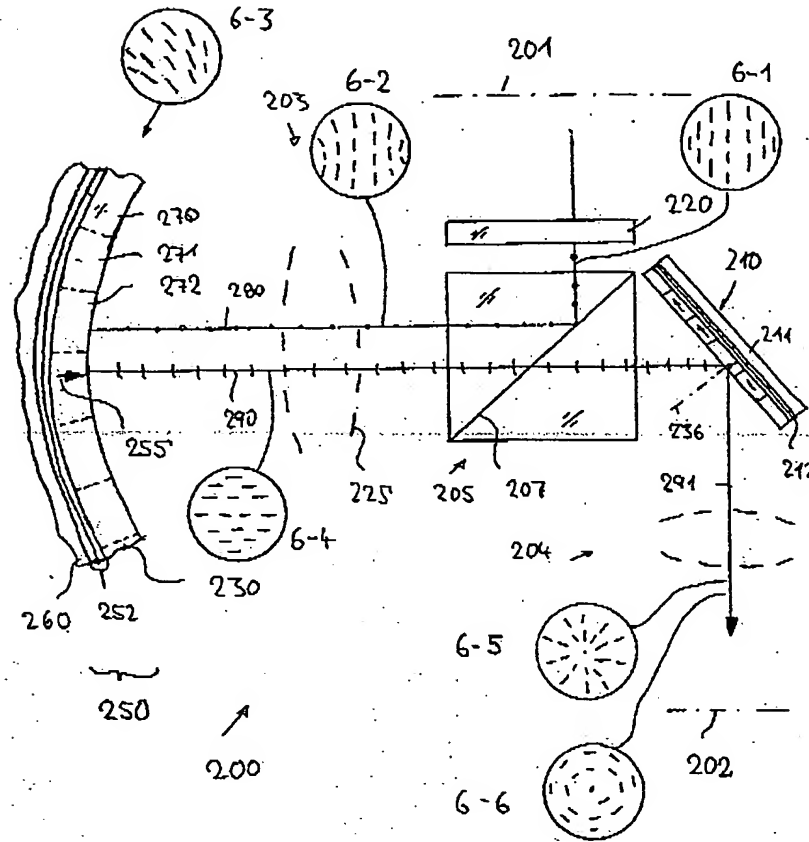
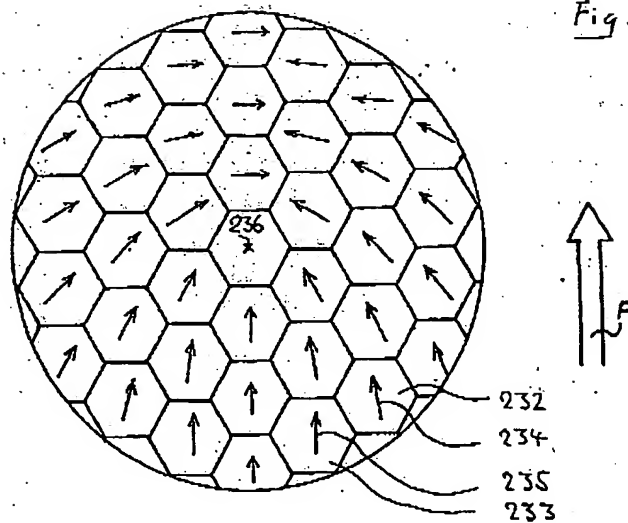
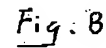


Fig. 6

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Fig. 7



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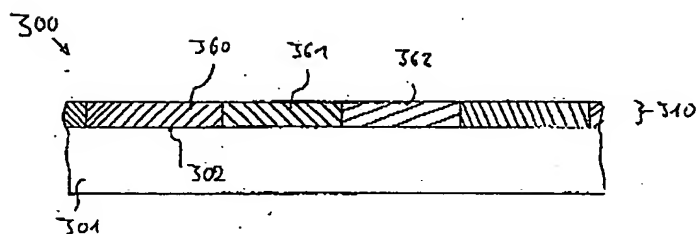


Fig. 9

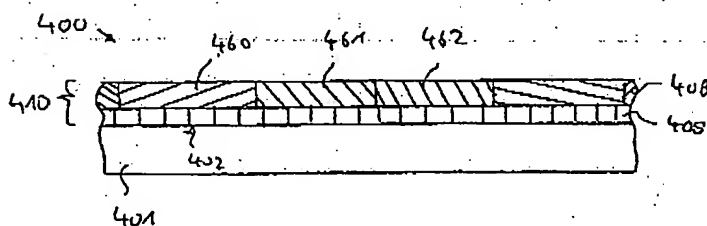


Fig. 10

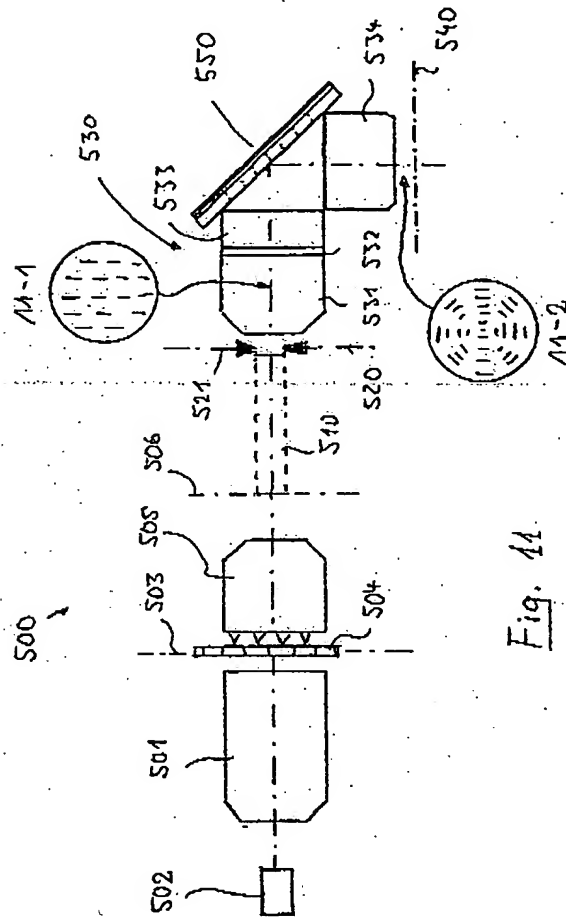


Fig. 11

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